



## On severi's proof of the double point formula

F. Catanese

To cite this article: F. Catanese (1979) On severi's proof of the double point formula , Communications in Algebra, 7:7, 763-773, DOI: [10.1080/00927877908822373](https://doi.org/10.1080/00927877908822373)

To link to this article: <http://dx.doi.org/10.1080/00927877908822373>



Published online: 27 Jun 2007.



Submit your article to this journal [↗](#)



Article views: 27



View related articles [↗](#)

ON SEVERI'S PROOF OF THE DOUBLE POINT FORMULA

F. Catanese  
 Univ. di Pisa  
 Harvard University\*

§0. Introduction

In his paper [6] of 1902 Severi considers the following situation: let  $M \longrightarrow \mathbb{P}^{2k}(\mathbb{C})$  be an irreducible variety of dimension  $k$  with "generic" singularities, i.e., only a finite number of transversal double points,  $P_1, \dots, P_d$  ("transversal" means that locally, at each  $P_i$ ,  $M$  consists of two smooth branches intersecting transversally).

Severi then gives a formula expressing  $d$  in terms of certain projective characters of  $M$ :

$$2d = n(n-1) - \sum_{i=1}^k \omega_i.$$

Here  $n$  is the degree of  $M$ , and  $\omega_i$  is the  $i^{\text{th}}$  ceto

---

\* The author was supported by a N.A.T.O.-C.N.R. fellowship during his stay at Harvard University.

of  $M$ , which can be conveniently defined as follows: if  $V \rightarrow \mathbb{P}^N$  is a variety of dimension  $m$ , the  $m^{\text{th}}$  ceto  $\omega_m(V)$  is the number of  $m$ -dimensional linear subspaces tangent to  $V$  at smooth points which meet a general  $2m$ -codimensional linear subspace, while  $\omega_i(V)$  is the  $i^{\text{th}}$  ceto of the intersection of  $V$  with a general  $(m-i)$ -codimensional linear subspace. During the past few years there has been a renewed interest in enumerative geometry and Severi's double point formula has been generalized to a greater extent (see [2], and especially [3] for wider historical and bibliographical references): we believe however it may be interesting to give in this note an account of Severi's elementary proof, clarifying it and filling in some details skipped in his paper [6].

We note that this proof works word by word in the case of any algebraically closed field of char. 0.

### Notations

$G(r, N)$  is the Grassmanian of  $r$ -dimensional linear subspaces of  $\mathbb{P}^N$ .

$O$  is a general point in  $\mathbb{P}^{2k}$ ,  $\sigma_0 \subset G(k, 2k)$  is the Schubert cell of the subspaces containing  $O$ ,

$\Sigma_0 \subset G(1, 2k)$  is defined analogously.

$f: M' \longrightarrow M \longrightarrow \mathbb{P}^{2k}$  is the normalization of  $M$  (so that  $f$  is an immersion).

$\mu: M' \longrightarrow G(k, 2k)$  is the Gauss map of  $f$ .

$P'_1, P''_1$  are the two distinct points in  $M'$  whose image is  $P_1$ .

$\varphi_0, \varphi_1$  are two general linear forms on  $\mathbb{P}^{2k}$ .

$S$  is the  $(2k-2)$ -dimensional linear subspace defined by

$$\varphi_0 = \varphi_1 = 0 \text{ and } H \text{ is the hyperplane spanned by } O, S.$$

$\Delta_M$  is the diagonal in  $M \times M$ .

### Steps of Proof.

- 1) The projection of  $M \cap H$  from  $O$  to  $S$  is a birational immersion and its image  $\tilde{M}$  has generic double points.
- 2) If  $\tilde{d}$  is the number of double points of  $\tilde{M}$ ,  $2\tilde{d} = 2d + \omega_k$ .

Theorem: Steps 1), 2) imply that  $2d = n(n-1) - \sum_{i=1}^k \omega_i$ .

Proof: By induction on  $k$ . For  $k = 1$  we have a plane curve with  $d$  nodes and of degree  $n$ : hence the equation is a particular case of the first Plücker formula. We remark then that by step 1)  $n(M) = n(\tilde{M})$ ,  $\omega_i(M) = \omega_i(\tilde{M})$  so that the inductive assumption plus step 2) imply the desired result.

§I. The basic construction ( $k > 1$ )

Consider in  $(M \times M - \Delta_M) \times G(1, 2k)$  the graph of the map which takes  $(P, Q)$  to the line joining them, and its closure  $\Lambda$  in  $(M \times M) \times G(1, 2k)$ :  $\Lambda$  is irreducible of dimension  $2k$ .

Denote by  $p: \Lambda \longrightarrow G(1, 2k)$  the canonical projection; set  $Z = p(\Lambda)$ .

Lemma 1:  $p: \Lambda \longrightarrow Z$  is generically a 2-1 map if  $M$  is not contained in a linear subspace of dimension  $k+1$  (note that if  $d \geq 1$ ,  $M$  is not contained in any hyperplane); in particular, then,  $Z$  is irreducible of dimension  $2k$ .

Proof: In our hypotheses you can find  $k+3$  points of  $M$  spanning a subspace of dimension  $k+2$ , so that a general subspace  $L$  of dimension  $k$  will be such that  $L \cap M$  is a finite set with the property that any  $k+3$  points in it are linearly independent (compare [0], chapter II, iii), "Special linear systems I"), hence a fortiori any line through two of them won't contain a third one: this however immediately implies our assertion.

Fix a general point  $O$  and denote by  $\hat{\gamma} = p^{-1}(\Sigma_O \cap Z)$ , by  $\hat{\gamma}'$  its inverse image in  $M' \times M' \times G(1, 2k)$ , by  $\gamma, \gamma'$  the respective projections on  $M, M'$ , by  $\tilde{\gamma}, \tilde{\gamma}'$  the projections on  $M \times M, M' \times M'$ .

Proposition 2:  $\tilde{\gamma}'$  is smooth;  $\tilde{\gamma}'$  is the graph of a birational involution  $\tau$  on  $\gamma'$  such that  $\tau(P'_1) = P''_1$ .

We first prove two auxiliary lemmas:

Lemma A: Let  $P$  be a smooth point of  $M$ , and  $O$  a point in the space  $T_P$  tangent to  $M$  at  $P$ . Then  $P \in \gamma$  and  $\gamma$  is smooth at  $P$  if  $\sigma_O$  is transversal to  $\mu(M')$  at  $\mu(P)$ ; in this case also  $(d\tau)_P = -\text{Identity}$ .

Proof: We can take affine coordinates  $x = (x_1, \dots, x_k)$ ,  $y = (y_1, \dots, y_k)$  so that  $P$  corresponds to the origin,  $y = 0$  is  $T_P$ ,  $O$  is the point at infinity on the  $x_1$ -axis:  $(x, f(x))$ , where  $f \in (\mathbb{A}_x^2)^k$ , will be then a parametric equation of  $M$  in a neighborhood  $U$  of  $P$ . Take coordinates  $(x, z)$  in  $U \times U$ : then the line through  $(x, f(x))$ ,  $(z, f(z))$  contains  $O \iff x_2 - z_2 = 0, \dots, x_k - z_k = 0$ , and  $f_h(x) - f_h(z) = 0$  for  $h = 1, \dots, k \iff x_2 - z_2 = 0, \dots, x_k - z_k = 0$

$$f_h(x_1, x_2, \dots, x_k) - f_h(z_1, x_2, \dots, x_k) = 0 \quad (h = 1, \dots, k).$$

We can write  $f_h(x_1, x_2, \dots, x_k) \equiv \sum_{v=0}^2 f_h^v(x_2, \dots, x_k) \cdot x_1^v \pmod{\mathbb{A}_x^3}$ ,

hence

$$f_h(x_1, x_2, \dots, x_k) - f_h(z_1, x_2, \dots, x_k) \equiv (x_1 - z_1) \left[ f_h^1 + (x_1 + z_1) f_h^2 \right] \pmod{\mathbb{A}_x^3};$$

if at the origin  $\det(f_h^2 \partial f_h^1 / \partial x_r) \neq 0$   $\left( \begin{array}{l} h = 1, \dots, k \\ r = 2, \dots, k \end{array} \right)$

then it is easily seen by the implicit function theorem that  $\tilde{\gamma}$  is smooth and  $x_1, z_1$  can be both chosen as a local coordinate (hence  $\gamma$  is smooth too). Moreover,

$f_h^2(0)(dx_1 + dz_1) = 0 \quad \forall h \implies dx_1 = -dz_1$  at  $P$ . We are going then to check the non-vanishing of our determinant.

In fact, the subspaces near  $T_P$  have parametric equations  $(w, Aw+b)$ ,  $\sigma_0$  consists locally of the submanifold defined by  $Ae_1 = 0$  (the first column of  $A$  must vanish), the Gauss map  $\mu$  takes  $x$  to  $A = (\partial f_h^1 / \partial x_r)$ ,  $b = f$ : hence transversality to  $\sigma_0$  at  $\mu(P)$  means that

$\partial f_h^1 / \partial x_1: U \longrightarrow \mathbb{C}^k$  has invertible differential at the origin.

But  $\partial f_h^1 / \partial x_1 \equiv f_h^1 + 2x_1 f_h^2 \pmod{\mathbb{C}[x]^2}$  so its Jacobian matrix is at the origin

$$\left( 2f_h^2 \partial f_h^1 / \partial x_r \right) \left( \begin{array}{l} h = 1, \dots, k \\ r = 2, \dots, k \end{array} \right).$$

We remark finally that the tangent to  $\gamma$  at  $P$  passes through  $O$ .

**Lemma B:** Let  $P$  be a double point of  $M$ : then if  $O$  does not belong to  $\mu(P')$ ,  $\mu(P'')$ ,  $\tilde{\gamma}'$  is smooth at  $(P', P'')$ ,  $\gamma'$  is smooth at  $P', P''$ ,  $\tau$  is biregular at  $P', P''$ .

Proof: We can take affine coordinates

$x = (x_1, \dots, x_k)$ ,  $y = (y_1, \dots, y_k)$  such that  $P$  is the origin,  $\mu(P')$  is  $y = 0$ ,  $\mu(P'')$  is  $x = 0$ . The two branches have parametric equations  $(x, f(x))$ , respectively  $(g(y), y)$ , ( $f \in (\mathbb{A}_x^2)^k$ ,  $g \in (\mathbb{A}_y^2)^k$ ). We can also suppose  $O$  to be the point at infinity on the line through  $P$  and  $((1, 0, \dots, 0), (1, 0, \dots, 0))$ , so that in a neighborhood of  $P$  two points of  $M$  can be collinear with  $O$  only if they lie in different branches.

$\tilde{Y}'$  is then defined locally by the following equations:

$$\begin{aligned} F_h &= y_h - f_h(x) = 0 \\ &h = 2, \dots, k \\ G_h &= x_h - g_h(y) = 0 \end{aligned}$$

and

$$G_1 = x_1 - g_1(y) - y_1 + f_1(x) = 0.$$

Clearly at the origin (corresponding to  $(P', P'')$ ),  $\partial G_h / \partial x_k = \delta_{hk}$ ,  $\partial F_h / \partial x_k = 0$ ,  $\partial F_h / \partial y_k = \delta_{hk}$ ,  $\partial G_h / \partial y_k = -\delta_{1h} \delta_{1k}$  so that by the implicit function theorem  $\tilde{Y}'$  is smooth and both  $x_1, y_1$  can be taken as a local coordinate.

Proof of Prop. 2: Observe that  $\Lambda$  is smooth outside  $\Delta_M \times G(1, 2k)$ : by theorem 2 of [1] (page 290), then  $\tilde{Y}$  is



smooth there, and ( $\Lambda$  being there a graph)  $\tilde{\gamma} - \Delta_M$  is smooth.

For general  $O$ ,  $\sigma_O$  has  $\omega_k$  transversal intersections with  $\mu(M')$  (by [1]) at  $\mu(Q_1), \dots, \mu(Q_{\omega_k})$ , where  $Q_j \neq P_i$ , hence we can apply Lemma A, and putting together with the above result and Lemma B we obtain that  $\tilde{\gamma}'$  is smooth. Moreover Lemma 1 guarantees that the projection from  $\tilde{\gamma}'$  to  $\gamma'$  is birational, and we observe for later use that the  $Q_i$  are the only fixed points of  $\tau$ .

Remark: Though  $\tilde{\gamma}'$  is smooth,  $\gamma'$  needs not to be so (a trisecant through  $O$  contributes three double points of  $\gamma$ ).

### §III. Proof of the main steps.

Step 1): For  $H$  general  $M \cap H$  is smooth of dimension  $k-1$  so you can find  $O \in H$  such that the projection of  $M \cap O$  with center  $O$  is a birational immersion and its image  $\tilde{M}$  has "generic" singularities. (This is well known, see e.g. [4]).

Step 1 +  $\frac{1}{2}$ ): For general  $O$ ,  $\gamma$ , you can find  $H$  a general hyperplane containing  $O$  such that

i)  $H$  intersects  $\gamma$  transversally in  $\deg \gamma$  distinct smooth points  $R_1, \dots, R_{\deg \gamma}$ .

ii)  $H$  contains no  $Q_i$  (so you can suppose  $\deg \gamma = 2m$  and  $\tau(R_i) = R_{m+i}$  for  $i \leq m$ ).

iii)  $H, O$  satisfy the requirements of step 1).

To check i), ii), one needs to consider that only  $\omega_k$  tangents of  $\gamma$  pass through  $O$ , so that the hyperplanes containing  $O$  and not satisfying i), ii) form a  $(2k-2)$ -dimensional subvariety.

Now for  $S$  a general  $(2k-2)$ -dimensional linear subspace of  $H$  the projection  $\pi: H - \{O\} \rightarrow S$  is such that  $\tilde{M} = \pi(M \cap H)$  has  $\tilde{d}$  double points corresponding to the pairs  $\{R_i, \tau(R_i)\}$  in  $H \cap \gamma$ , hence  $m = \tilde{d}$ .

Step 2): Take  $\varphi_0$  a linear form vanishing on  $H$ ,  $\varphi_1$  a general one,  $S$  defined by  $\varphi_0 = \varphi_1 = 0$ . We will have  $\gamma \cap S = \emptyset$  and  $(\varphi_0, \varphi_1)$  defines a morphism  $g: \mathbb{P}^{2k-S} \rightarrow \mathbb{P}^1$ , and naturally

$$(g \circ f, g \circ f): (M' - f^{-1}(S)) \times (M' - f^{-1}(S)) \rightarrow \mathbb{P}^1 \times \mathbb{P}^1;$$

denote by  $\psi$  its restriction to  $\tilde{\gamma}'$ , by  $D = \psi(\tilde{\gamma}')$ , by  $\Delta$  the diagonal in  $\mathbb{P}^1 \times \mathbb{P}^1$ .

Because  $O, P, \tau(P)$  are collinear, it is clear that  $g(P) = g(\tau(P))$  iff either  $P = \tau(P)$  or  $P \in H$ , hence  $\psi^{-1}(\Delta)$  consists of the pairs  $(R_i, \tau(R_i)), (P'_j, P''_j), (P''_j, P'_j), (Q_h, Q_h)$ .

Assertion: For general  $\varphi^1$ ,  $\psi$  is transversal to  $\Delta$ ,  
 $\psi(Q_i, Q_i) \neq \psi(Q_j, Q_j)$  for  $i \neq j$  ( $\iff g(Q_i) \neq g(Q_j)$ ).

As a first consequence of this we get that  
 $\psi^{-1}((Q_i, Q_i)) = (Q_i, Q_i)$  so that  $\psi$  is birational, hence  $D$   
 has bidegree  $(2\tilde{d}, 2\tilde{d})$ : in fact, if  $(\mu_0, \mu_1) \in \mathbb{P}^1$ , the  
 intersections of  $D$  with  $(\mu_0, \mu_1) \times \mathbb{P}^1$  correspond then to  
 the points of  $\gamma$  in the hyperplane  $\mu_1 \varphi_0 - \mu_0 \varphi_1 = 0$ , and are  
 then  $2\tilde{d} = \deg \gamma$ , and moreover  $D$  is clearly symmetric in  
 $\mathbb{P}^1 \times \mathbb{P}^1$ . As a second consequence  $D \cdot \Delta = 2\tilde{d} + 2d + \omega_k$ :  
 but, having computed the bidegree of  $D$ , we know also  
 that  $D \cdot \Delta = 4\tilde{d}$ , hence we infer that  $2\tilde{d} = 2d + \omega_k$ .

Proof of the assertion: By Lemma A, B, we must prove  
 that  $g$  has maximal rank at each  $Q_j$ , at each  $R_j$  and  $P_h$   
 $g \cdot f$  and  $g \cdot f \cdot \tau$  have not the same differential, the  $Q_j$ 's  
 have all distinct images.

If  $P$  is any of these points, take a nonzero tangent  
 vector  $t_P$  of  $\gamma'$  at  $P$  and pick a hyperplane  $H'$  in  $\mathbb{P}^{2k}$  not  
 containing  $f(P)$  for any of these points: then on  $\mathbb{P}^{2k-H'}$   
 choose affine coordinates  $(z_1, \dots, z_{2k})$  such that

$$g = (\varphi_0, \varphi_1) = (z_1, a_0 + \sum_{i=1}^{2k} a_i z_i).$$

You can then identify  $f(P), df(t_p)$  to a point and an applied vector at it in this affine space, and if  $f(P) = f(\tau P), df(t_p) \neq d(f \cdot \tau)(t_p)$ : what we want then is that  $g$  must separate a finite number of points (including the vertices of the applied vectors), for which  $z_1 \neq 0$ , and this can clearly be achieved for general  $a_i$ 's.

## REFERENCES

- [0] P. Griffiths, J. Harris, "Principles of algebraic geometry", Wiley Interscience (1978).
- [1] S.L. Kleiman, "The transversality of a general translate", *Comp. Math.*, 28, Fasc. 3 (1974), pp. 287-297.
- [2] S.L. Kleiman, "Problem 15. Rigorous foundation of Schubert's enumerative calculus", *Proce. of Symp. in Pure Math.*, 28, A.M.S. Providence (1976).
- [3] S.L. Kleiman, "The enumerative theory of singularities", to appear in *Proc. Oslo Nordic Summer School* (1976).
- [4] J.N. Mather, "Stable map germs and algebraic geometry", *Springer Lecture Notes* 197 (1971), pp. 176-193.
- [5] F. Severi, "Intorno ai punti doppi impropri di una superficie generale dello spazio a quattro dimensioni e ai suoi punti triple apparenti", *Rend. Circ. Mat. di Palermo*, 15, (1901), pp. 33-51; also in *Memorie Scelte*, I, Zuffi (Bologna) (1950).
- [6] F. Severi, "Sulle intersezioni delle varietà algebriche e sopra i loro caratterie singolarità proiettive", *Mem. Accad. Scienze di Torino*, S. II, 52, (1902), pp. 61-118; also in *Memorie Scelte*, I, Zuffi (1950) (Bologna).